

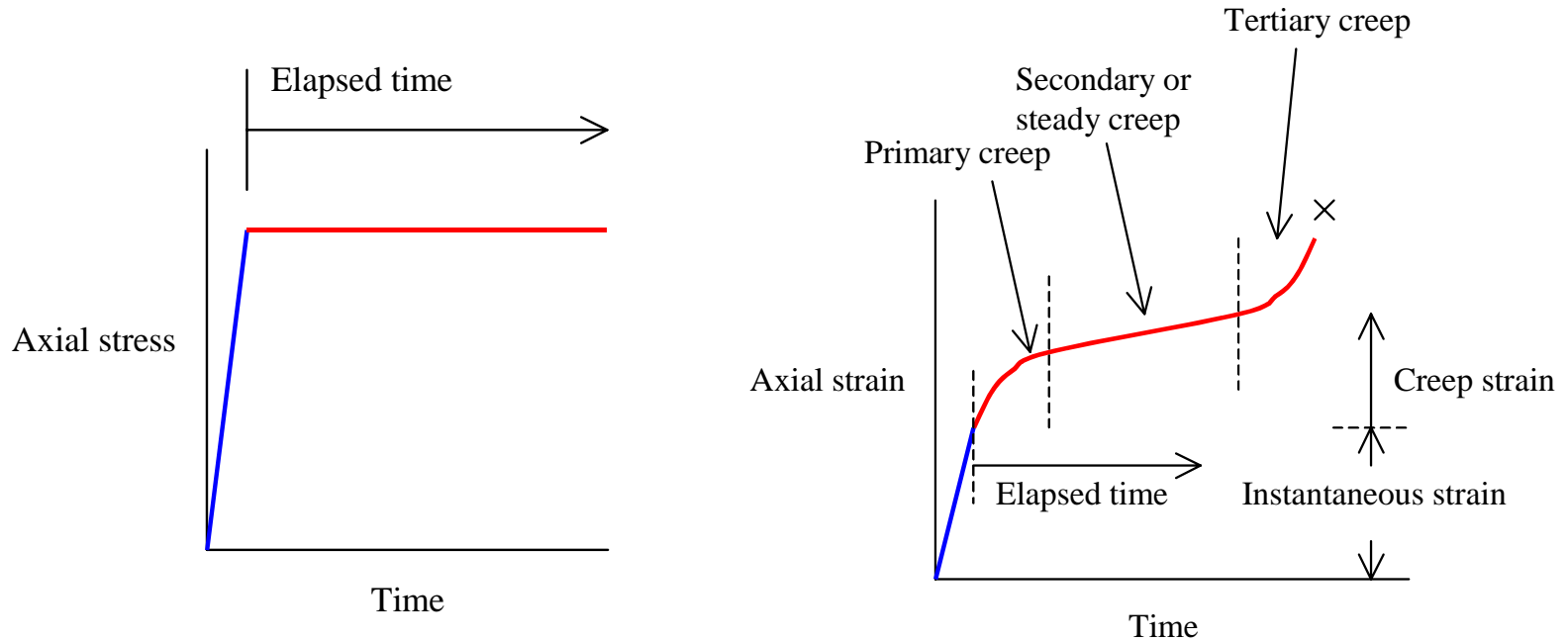
6. Creep and fatigue failure

‡: このマークが付してある著作物は、第三者が有する著作物ですので、同著作物の再使用、同著作物の二次的著作物の創作等については、著作権者より直接使用許諾を得る必要があります。

6.1 Creep as a phenomena

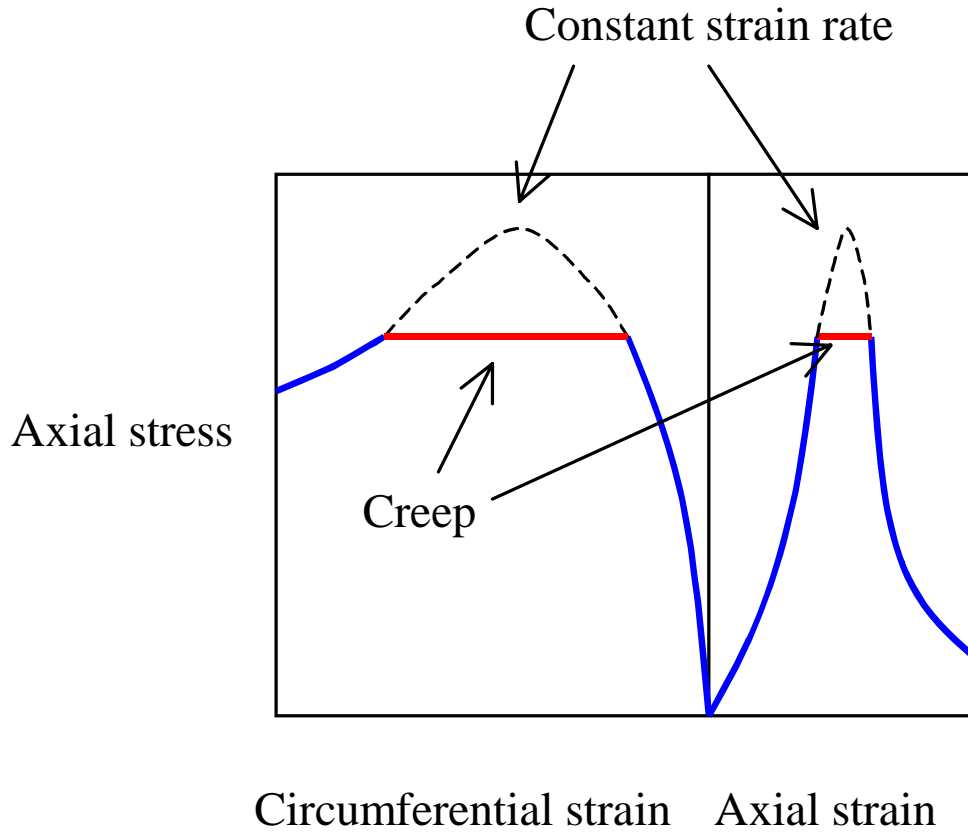
Creep

- Strain increases under a constant stress

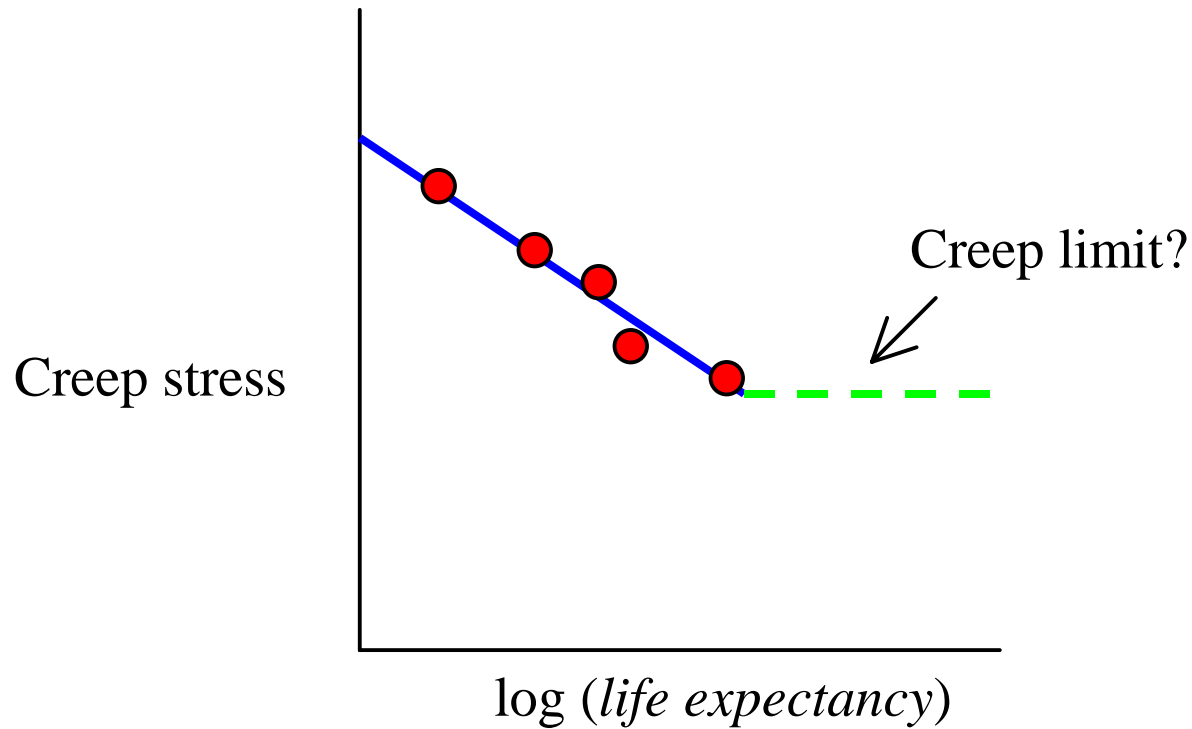


Why creep?

- Failure of rock mass around tunnel
- Failure of rock slope
 - with trigger
 - pore pressure, thermal stress, freeze thaw cycle, weathering, etc.
 - without trigger
 - creep



Creep stress and time to failure



- Q: Time to failure of a rock is 3.6×10^3 s and 3.6×10^4 s under 100 MPa and 80 MPa of creep stress, respectively. Estimate time to failure under 85 MPa of creep stress.
- A: 20230 s

Strain rate in secondary creep

$$\dot{\varepsilon} = A \sigma^n$$

$\dot{\varepsilon}$: strain rate

A : constant

σ : creep stress

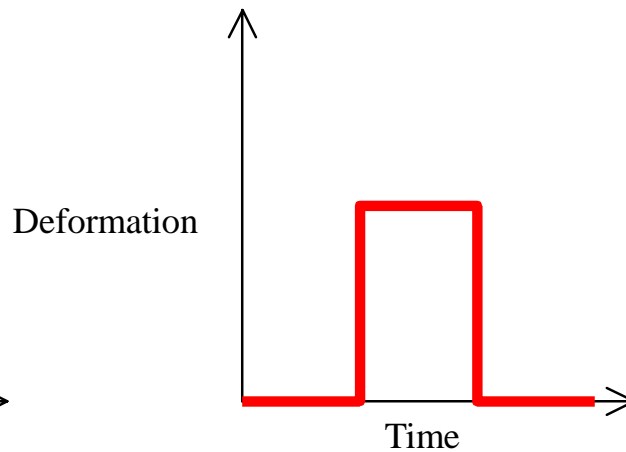
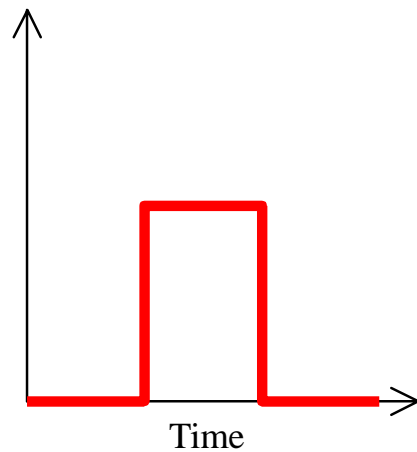
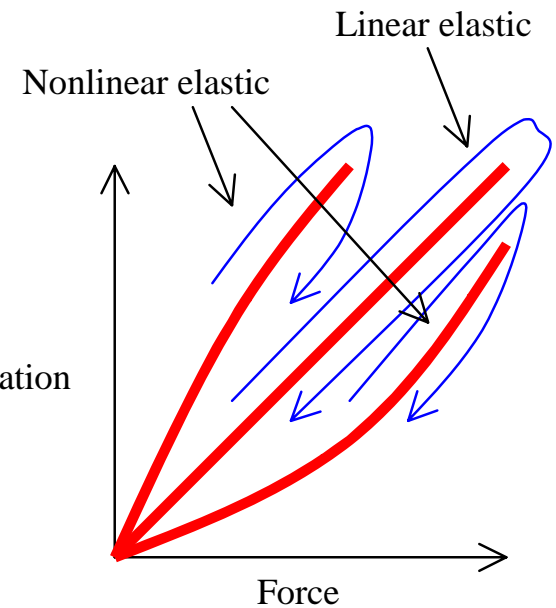
n : constant (20~50)

6.2 Mechanical properties of bodies

6.2.1 Elasticity, viscosity and plasticity

Elasticity

- Elastic body deforms when subjected to force
- Deformation vanishes when force is removed
- Example of elastic bodies
 - Springs, rubber

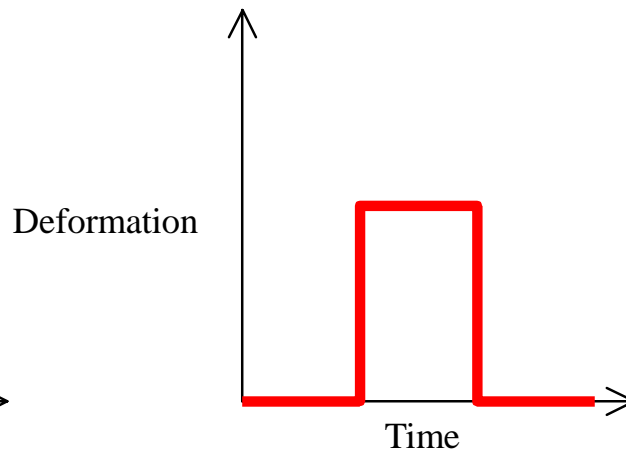
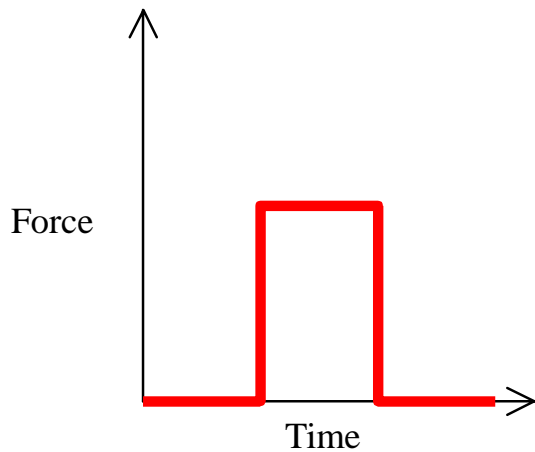
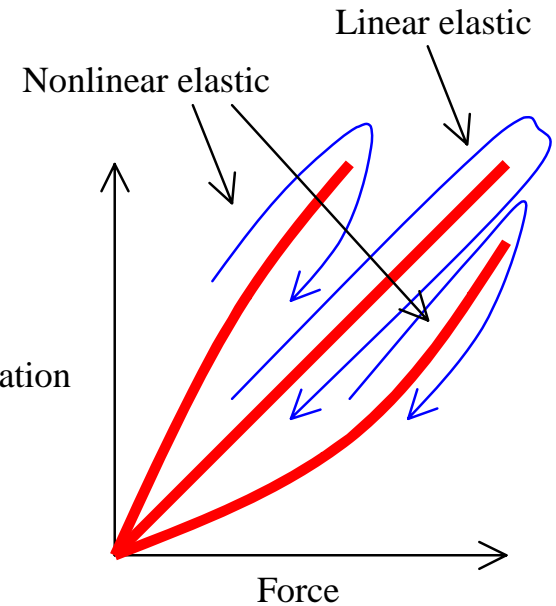


Linear elastic body

- Spring is used as an element body

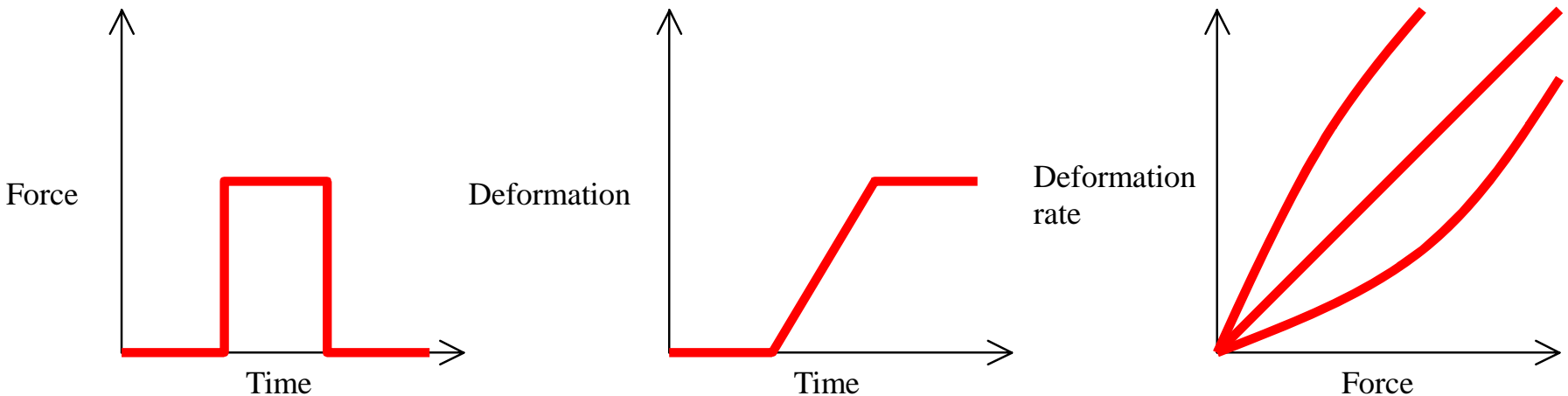


$$\varepsilon = \frac{\sigma}{E}$$

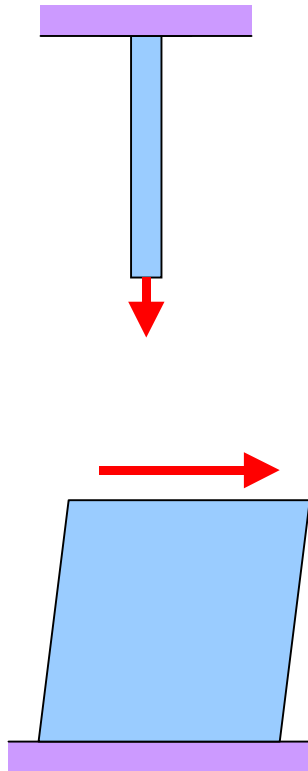


Viscosity

- Deformation continues under constant force
- Deformation does not vanish when force is removed
- Oil, candy etc.



Newtonian body



$$\sigma = \eta \dot{\epsilon}$$

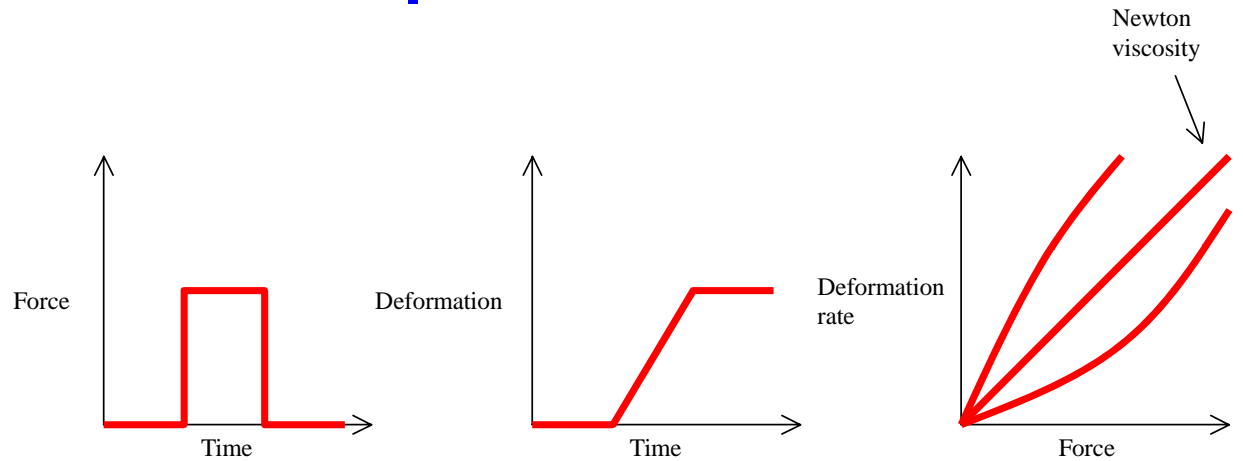
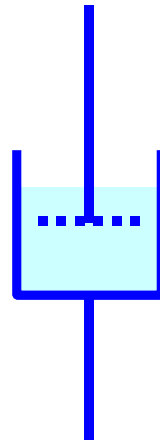
σ	Normal stress
η	Normal viscosity
$\dot{\epsilon}$	Strain rate

$$\tau = \mu \dot{\gamma}$$

τ	Shear stress
μ	Viscosity
$\dot{\gamma}$	Rate of shear

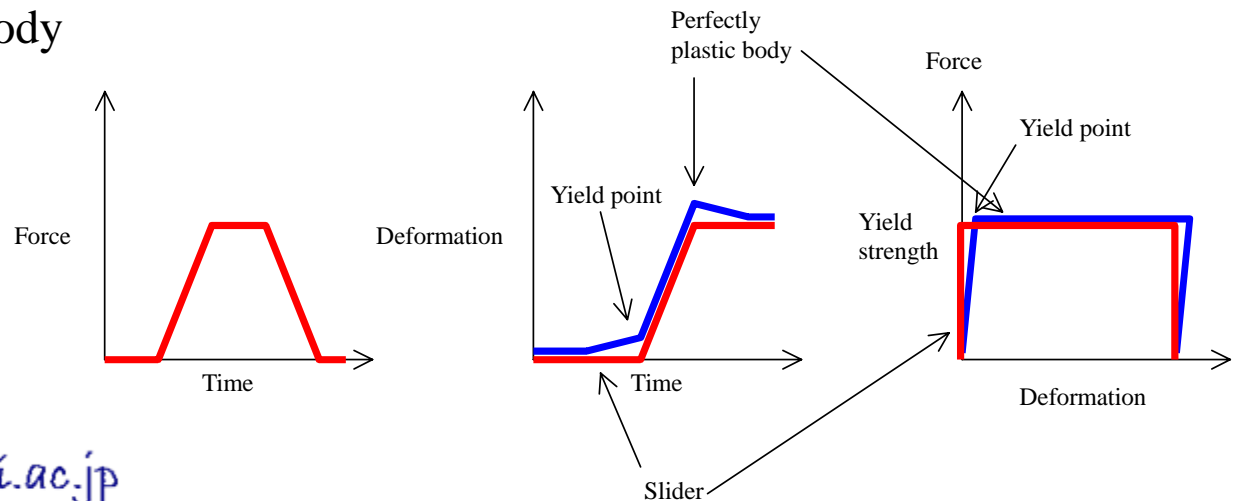
An element body for Newtonian body

- Dashpot is used

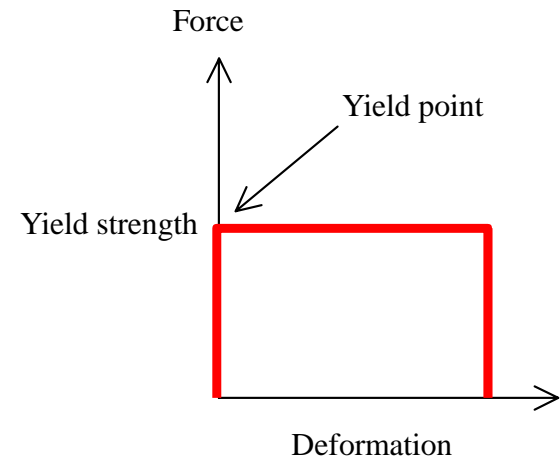
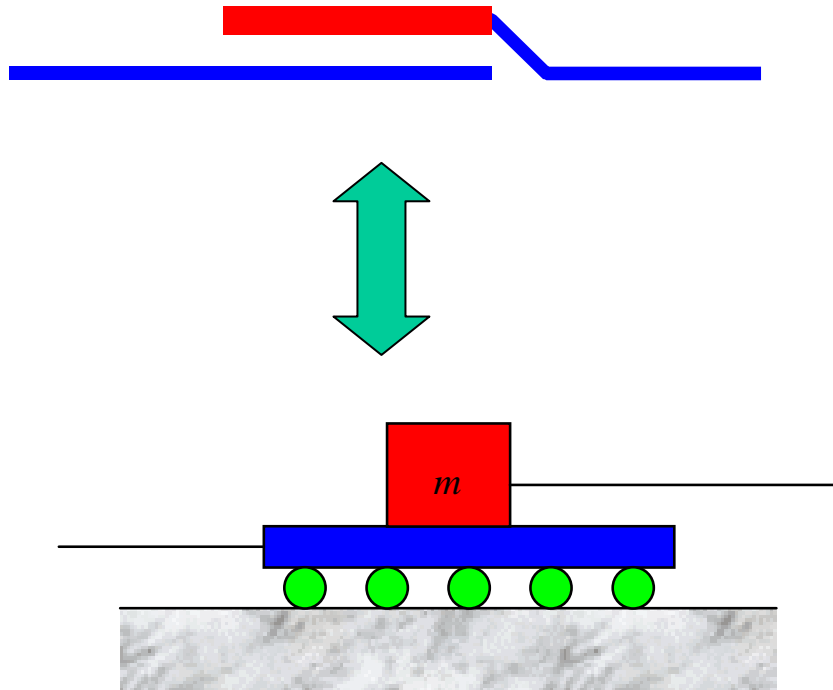


Plasticity

- Yield and deformation occurs at a stress
- Deformation does not vanish when stress is removed
 - Clay etc.
- A body which does not deform until yield point
 - Slider is used for an element body
- A body which shows elastic deformation until yield point
 - Perfectly plastic body



Slider?



Yield strength = Maximum value of frictional force = μmg

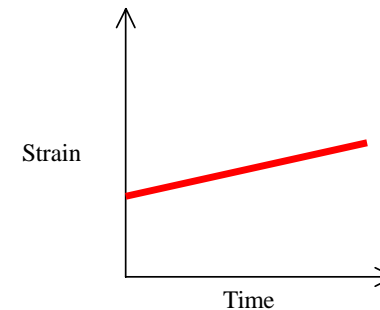
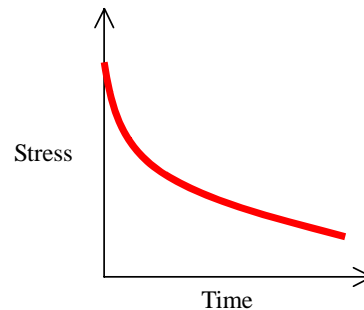
where μ is the friction coefficient

6.2.2 Mechanical model

Maxwell body

- One of the models which shows visco-elasticity
 - Stress relaxation occurs when stress is kept constant
 - Strain increases under constant stress

- Sticky candy etc.



$$\frac{d\sigma}{dt} = E \frac{d\varepsilon_s}{dt}$$

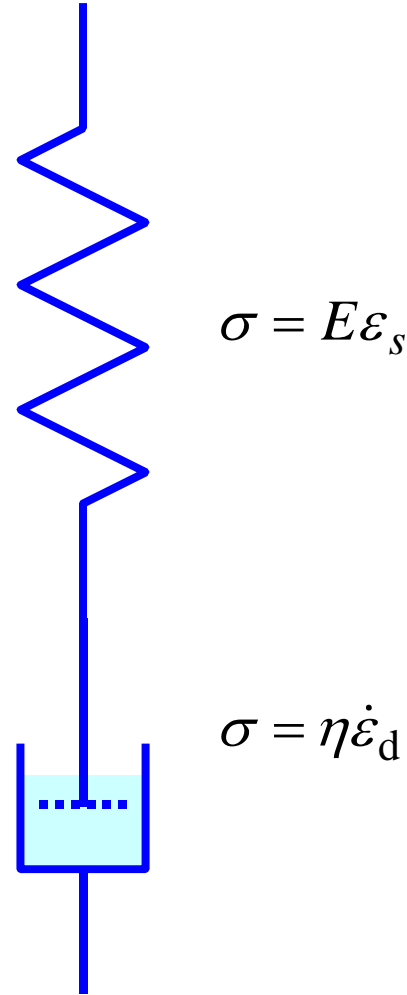
Total strain ε is

$$\varepsilon = \varepsilon_s + \varepsilon_d$$

Therefore

$$\begin{aligned} \frac{d\varepsilon}{dt} &= \frac{d\varepsilon_s}{dt} + \frac{d\varepsilon_d}{dt} \\ &= \frac{1}{E} \frac{d\sigma}{dt} + \frac{\sigma}{\eta} \end{aligned}$$

(Maxwell equation)



Constant strain

Assume that strain is kept constant in

$$\frac{d\varepsilon}{dt} = \frac{1}{E} \frac{d\sigma}{dt} + \frac{\sigma}{\eta}$$

Then,

$$0 = \frac{1}{E} \frac{d\sigma}{dt} + \frac{\sigma}{\eta}$$

$$\frac{1}{E} \frac{d\sigma}{dt} = -\frac{\sigma}{\eta}$$

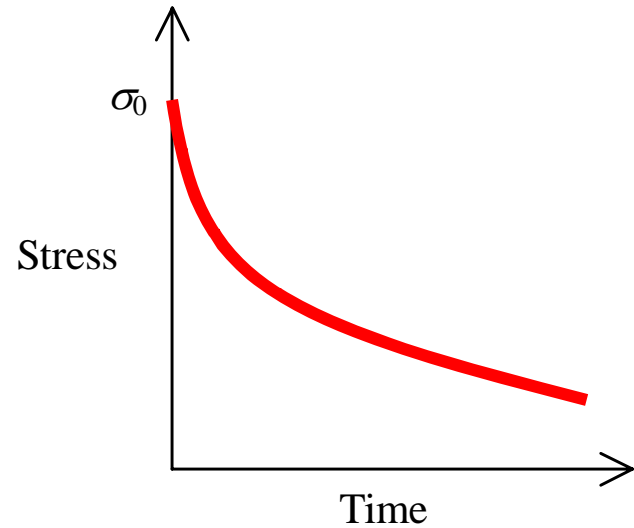
$$\frac{1}{E} \frac{d\sigma}{\sigma} = -\frac{1}{\eta} dt$$

$$\frac{\ln \sigma}{E} = -\frac{t}{\eta} + C_1$$

$$\sigma = \exp\left(-\frac{Et}{\eta} + C_1\right) = \exp(C_1) \exp\left(-\frac{Et}{\eta}\right)$$

Assume that $\sigma = \sigma_0$ at $t = 0$,

$$\sigma = \sigma_0 \exp\left(-\frac{Et}{\eta}\right)$$



Stress relaxation

Constant stress

Assume constant stress in

$$\frac{d\varepsilon}{dt} = \frac{1}{E} \frac{d\sigma}{dt} + \frac{\sigma}{\eta}$$

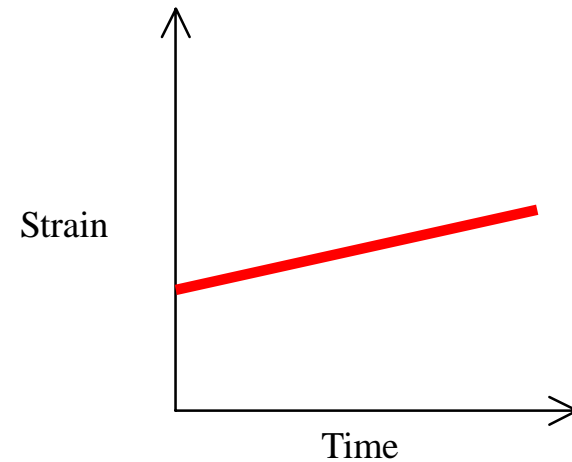
Then,

$$\frac{d\varepsilon}{dt} = \frac{\sigma}{\eta}$$

$$\varepsilon = \frac{\sigma}{\eta} t + C_1$$

Since $\varepsilon = \frac{\sigma}{E}$ at $t = 0$,

$$\varepsilon = \frac{\sigma}{E} + \frac{\sigma}{\eta} t$$

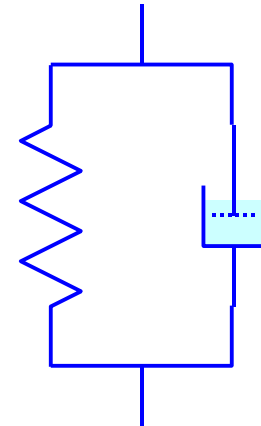
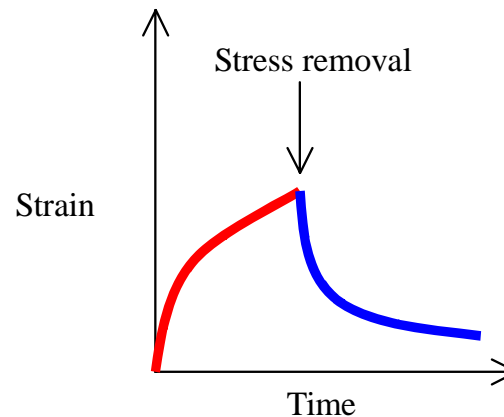


Viscous deformation

Voigt body (Kelvin body)

- One of the models for visco-elastic body
 - Strain increases with decreasing strain rate under constant stress
 - Strain decreases with decreasing strain rate when stress is removed

■ Nylon etc.



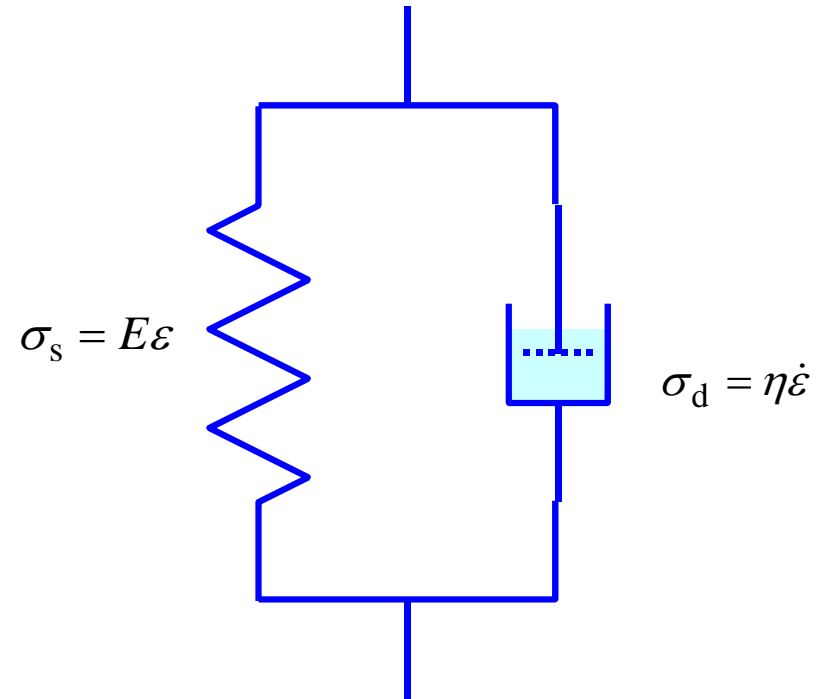
Total stress σ is

$$\sigma = \sigma_s + \sigma_d$$

Therefore,

$$\sigma = E\varepsilon + \eta \frac{d\varepsilon}{dt}$$

(Voigt or Kelvin equation)



In the case where stress is kept constant
between $t = 0$ and $t = t_1$

$$\sigma = E\varepsilon + \eta \frac{d\varepsilon}{dt}$$

$$\eta \frac{d\varepsilon}{dt} = -E\varepsilon + \sigma$$

$$\frac{d\varepsilon}{-E\varepsilon + \sigma} = \frac{1}{\eta} dt$$

$$-\frac{\ln(-E\varepsilon + \sigma)}{E} = \frac{t}{\eta} + C_1$$

$$\ln(-E\varepsilon + \sigma) = -E \frac{t}{\eta} + C_2$$

$$-E\varepsilon + \sigma = \exp C_2 \exp\left(-E \frac{t}{\eta}\right)$$

retarded elasticity

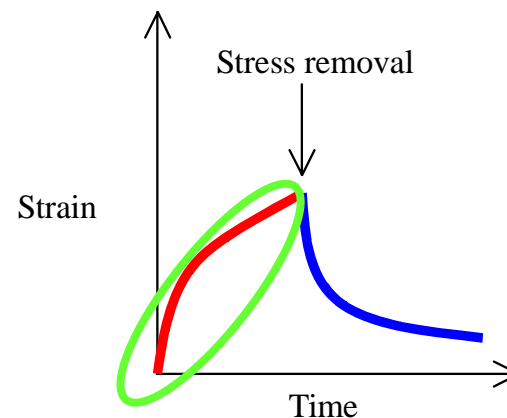
$$-E\varepsilon = \exp C_2 \exp\left(-E \frac{t}{\eta}\right) - \sigma$$

$$\varepsilon = C_3 \exp\left(-E \frac{t}{\eta}\right) + \frac{\sigma}{E}$$

Assuming that $\varepsilon = 0$ when $t = 0$,

$$\varepsilon = -\frac{\sigma}{E} \exp\left(-E \frac{t}{\eta}\right) + \frac{\sigma}{E}$$

$$\varepsilon = \frac{\sigma}{E} \left\{ 1 - \exp\left(-E \frac{t}{\eta}\right) \right\}$$



Then, unloaded

Substituting $\sigma = 0$, $t = t_1$ and strain at $t = t_1$

$$\varepsilon = C_3 \exp\left(-E \frac{t}{\eta}\right) + \frac{\sigma}{E}$$

into

$$\varepsilon = \frac{\sigma}{E} \left\{ 1 - \exp\left(-E \frac{t_1}{\eta}\right) \right\}$$

we get

$$\frac{\sigma}{E} \left\{ 1 - \exp\left(-E \frac{t_1}{\eta}\right) \right\} = C_3 \exp\left(-E \frac{t_1}{\eta}\right)$$

Therefore

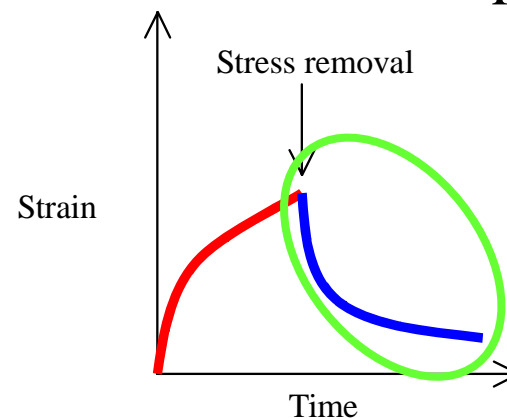
$$C_3 = \frac{\frac{\sigma}{E} \left\{ 1 - \exp\left(-E \frac{t_1}{\eta}\right) \right\}}{\exp\left(-E \frac{t_1}{\eta}\right)}$$

Hence,

$$\varepsilon = \frac{\frac{\sigma}{E} \left\{ 1 - \exp\left(-E \frac{t_1}{\eta}\right) \right\}}{\exp\left(-E \frac{t_1}{\eta}\right)} \exp\left(-E \frac{t}{\eta}\right)$$

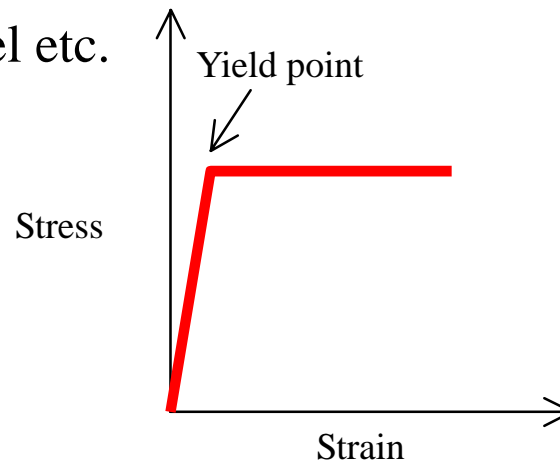
$$\varepsilon = \frac{\sigma}{E} \left\{ 1 - \exp\left(-E \frac{t_1}{\eta}\right) \right\} \exp\left(-E \frac{t-t_1}{\eta}\right)$$

retarded elasticity



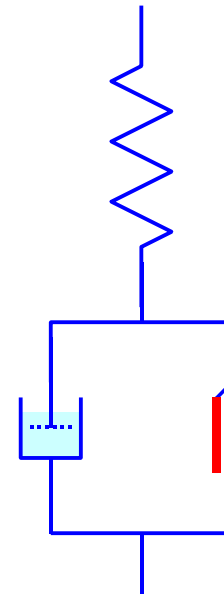
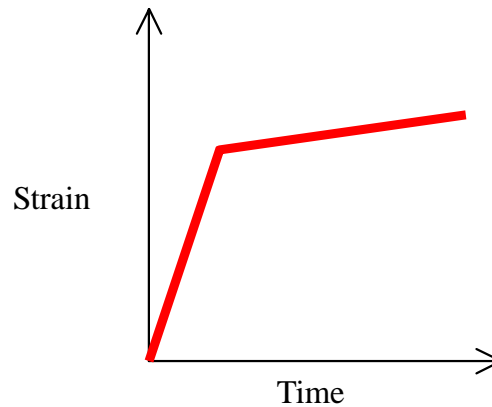
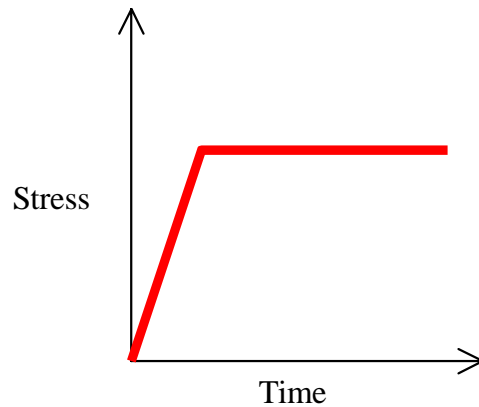
St. Venant body

- Elasto-plastic body
- Elastic deformation until yield point
- Plastic deformation after yield point
- Tooth paste, mild steel etc.



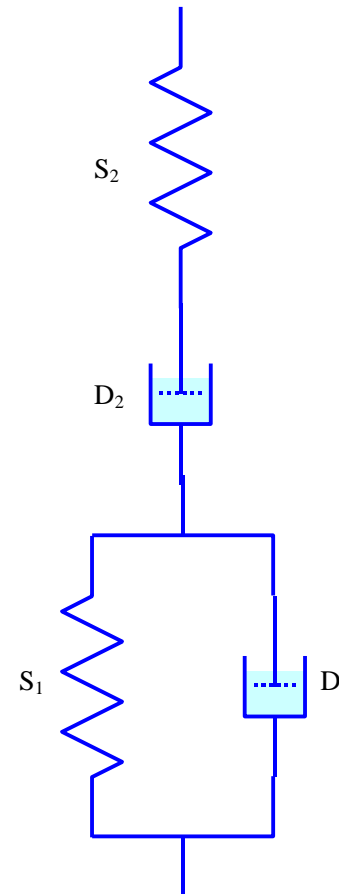
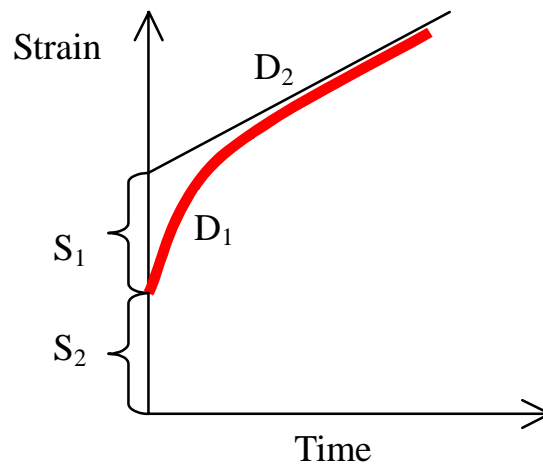
Bingham body

- A model for Visco-elasto-plastic body
- Elastic deformation until yield point
- Viscous deformation after yield point



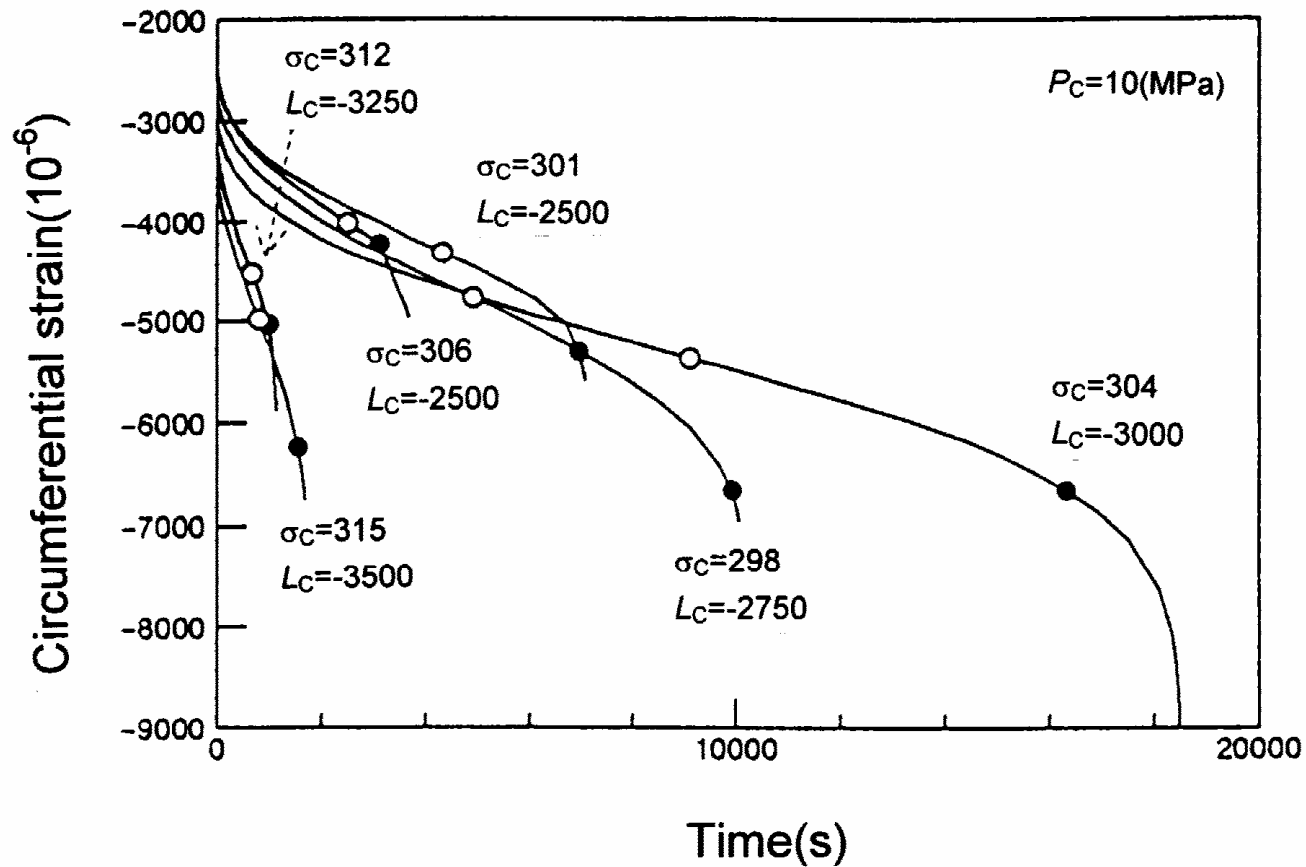
Mechanical model for creep deformation of rock

- Burgers model for primary and steady creep
- Tertiary creep can not be easily represented.

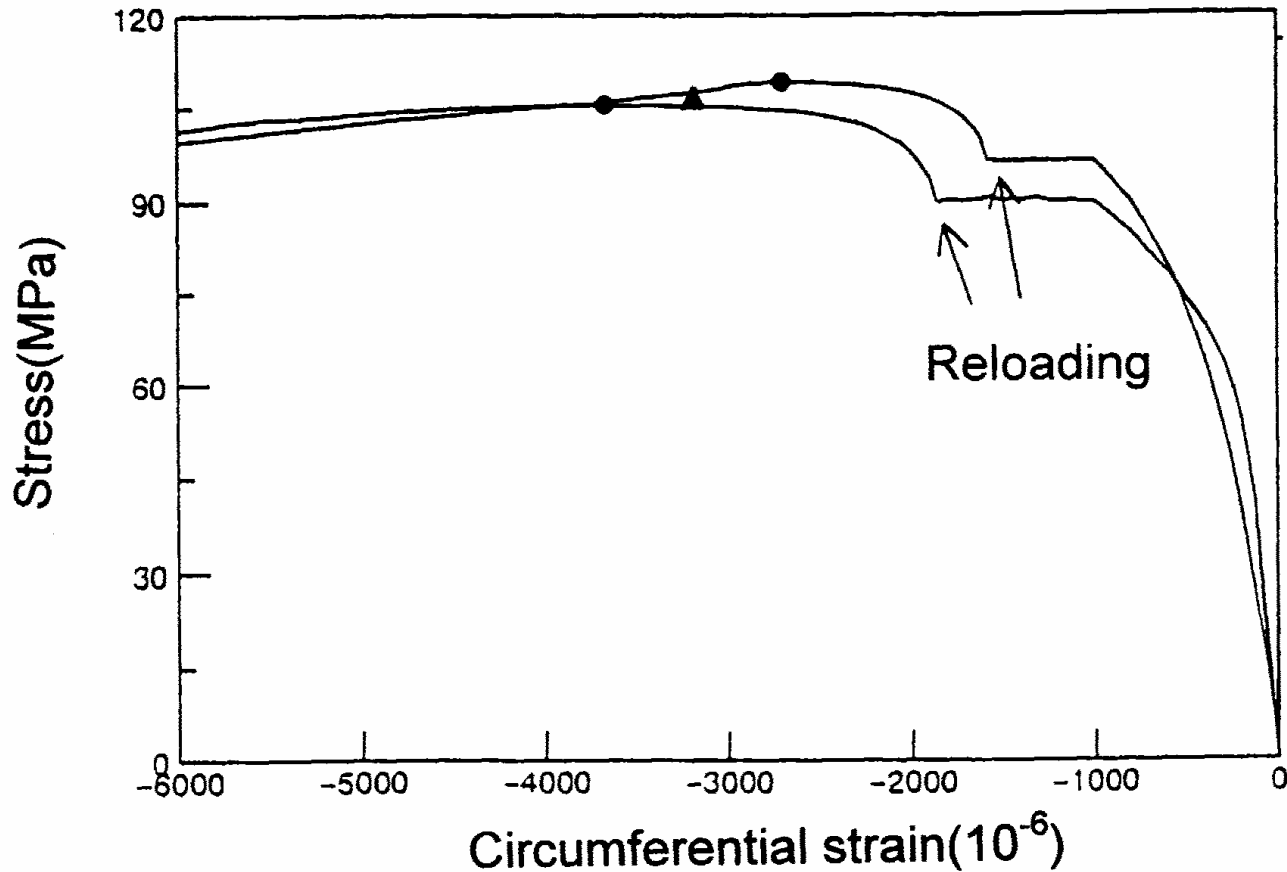


6.3 Example of creep test

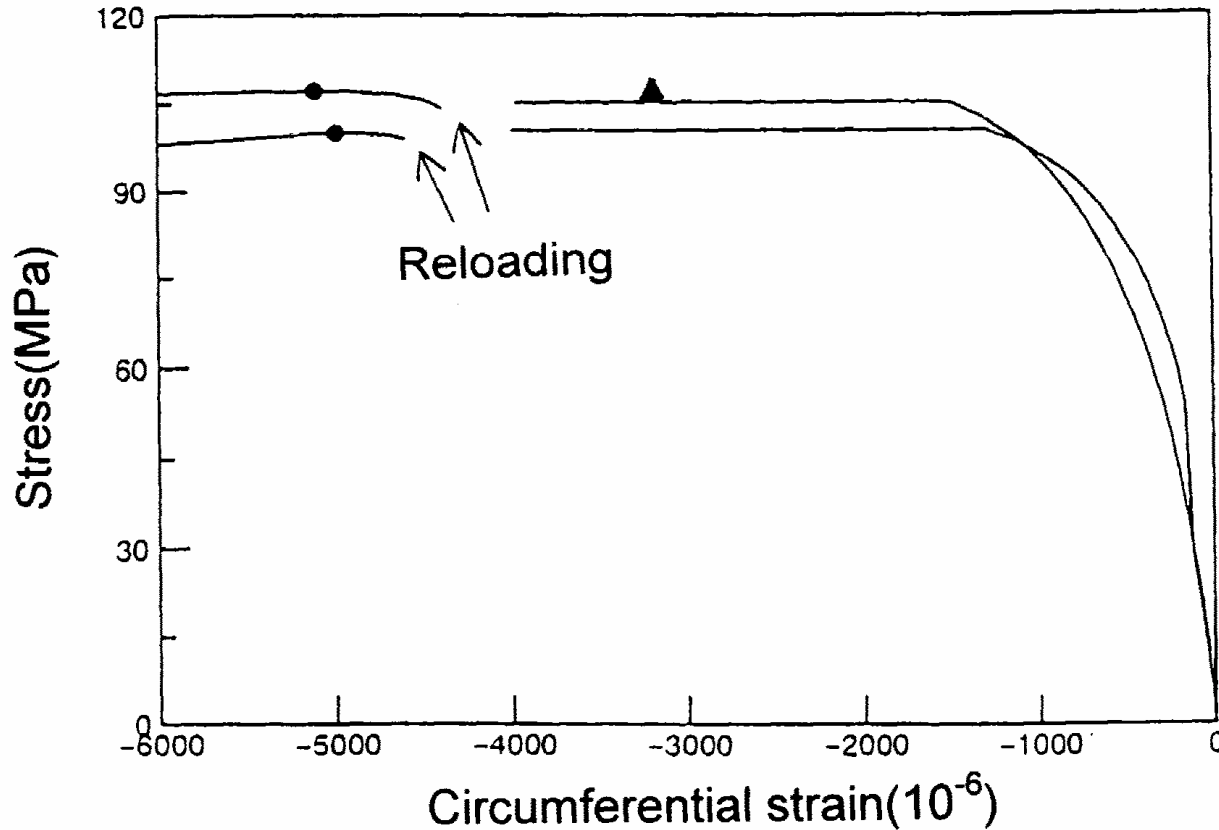
Creep behavior in circumferential strain



Damage of rock



The same strength can be attained when the specimen is reloaded before minimum circumferential strain rate is attained.



Peak stress is less than that in constant strain rate test when the specimen is reloaded after minimum circumferential strain rate is attained.

6.4 Mechanism of creep

Main causes of creep

- Change in distance between mineral particles
 - Migration of pore water, shear displacement, detachment etc.

- Deformation of mineral particles
 - Pressure solution, diffusion, dislocation etc.

- Subcritical crack growth
 - Stress corrosion etc.

Migration of pore water

- Finite velocity in migration of pore water due to pressure gradient by specimen deformation.
 - Hydraulic conductivity
 - Viscosity
 - Temperature
- The primary creep can be explained by homogenization of pore pressure.
- Effect of temperature can be explained.

Pressure solution

- Quartz etc. can be dissolved in pore water by high stress concentration at contact points.
- The solution migrates by grain boundary diffusion etc.
- Quartz etc. are precipitated at low stress-region.
 - Primary creep can be explained by the increase of contacted area.
 - Effects of temperature, pH etc. can be explained?

Diffusion creep

■ Homogenization of density

- Voids: from a grain boundary under tension to that under compression
- Atoms: from a grain boundary under compression to that under tension

Let L be the grain size. The density gradient is $\frac{\sigma}{L}$,

In the diffusion inside the grain, displacement rate is

proportional to density gradient, $C \frac{\sigma}{L}$,

strain rate is, dividing the displacement rate by the grain size,

$$\dot{\varepsilon} = C \frac{\sigma}{L^2}$$

In the grain boundary diffusion, cross sectional area is WL

where W is the thickness of grain boundary. The area is $\frac{WL}{L^2}$ times

the grain boundary diffusion case. Therefore,

$$\dot{\varepsilon} = \frac{C\sigma W}{L^3}$$

- Strain rate in diffusion creep
 - Inversely proportional to square or cube of the grain size
 - Proportional to creep stress

- Diffusion creep can be observed for metals and ceramics under low creep stresses.

- Existence of diffusion creep in minerals and rocks has not been proven.

Dislocation creep

Edge dislocation

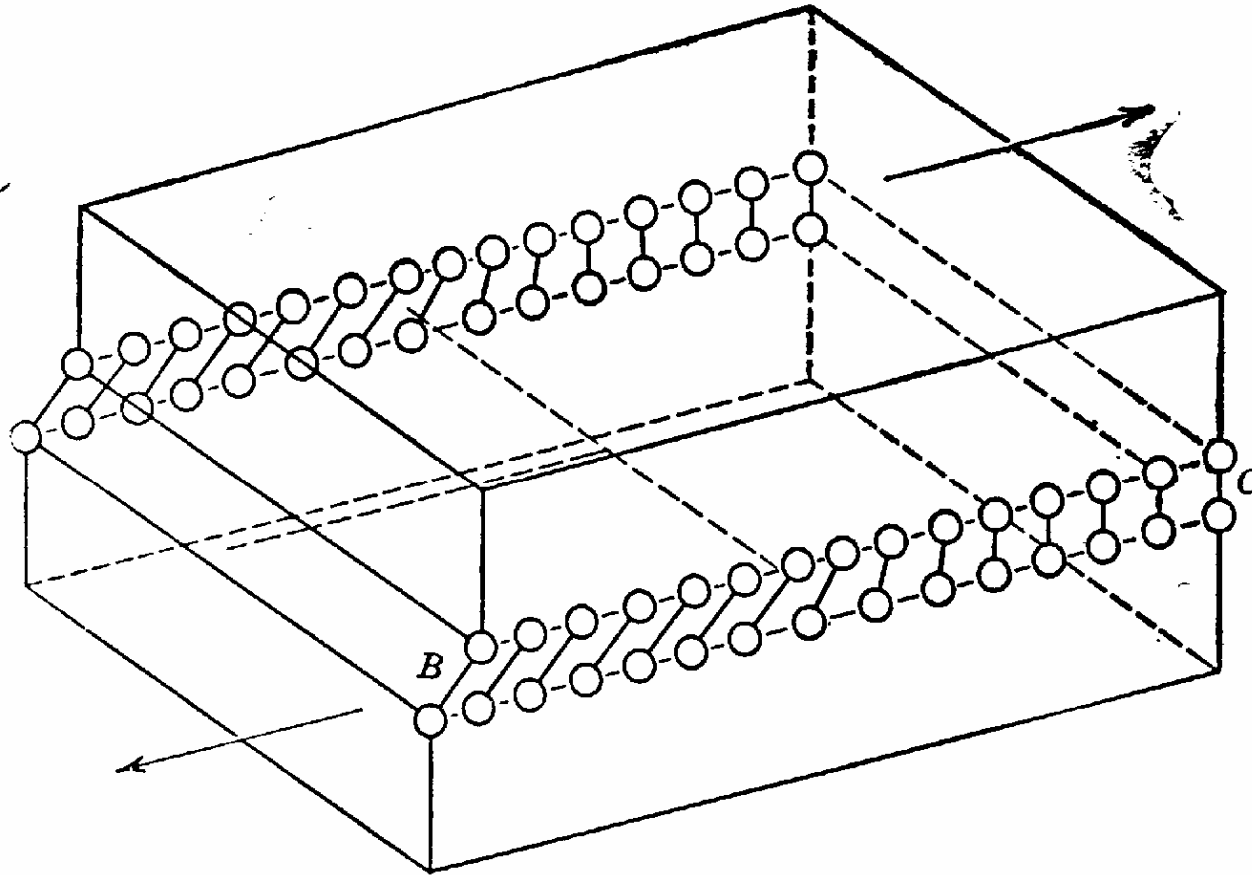


図 11-2 スリップによって生じた刃状転位*

制限資料

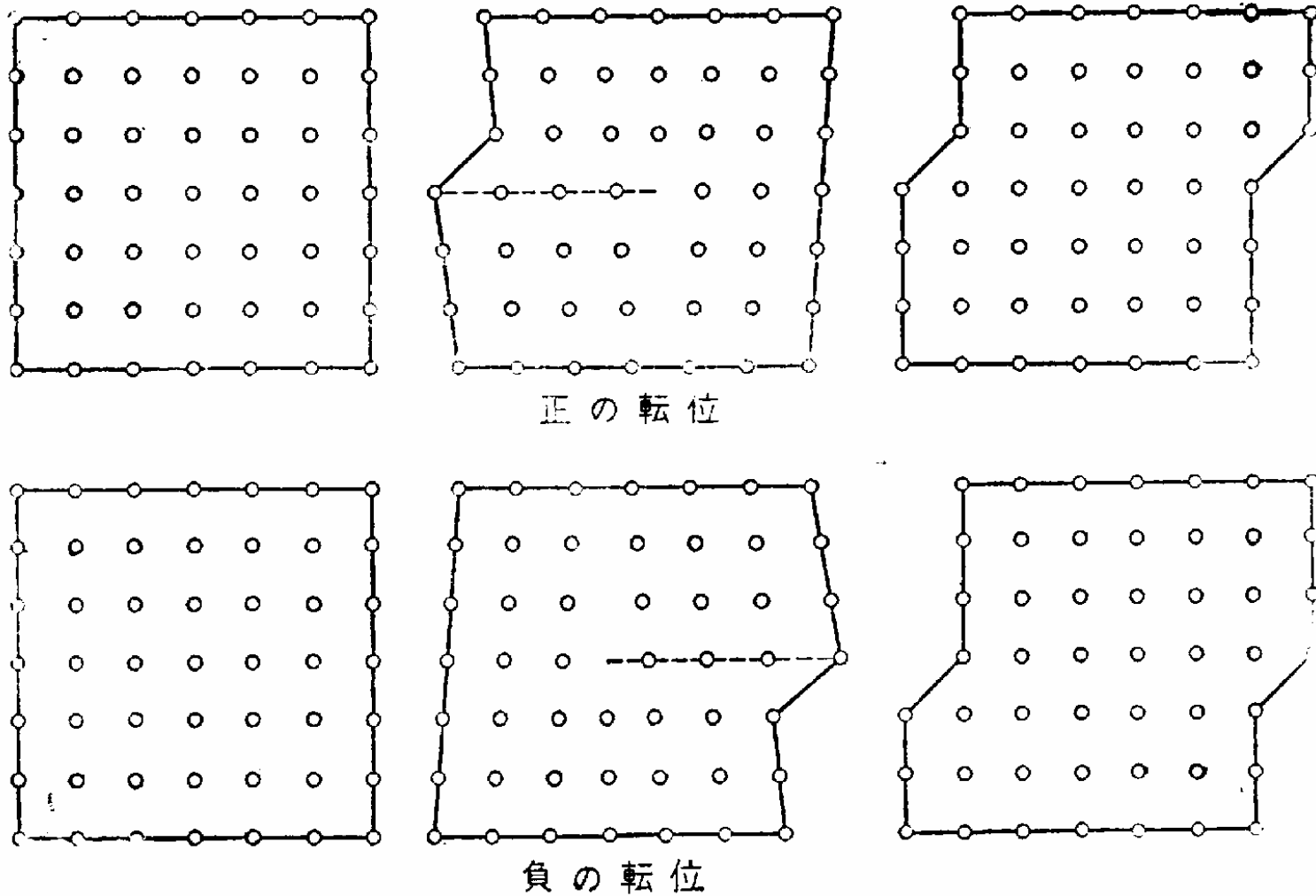


図 11-3 スリップを作る転位の動きの説明図**

制限資料

Screw dislocation

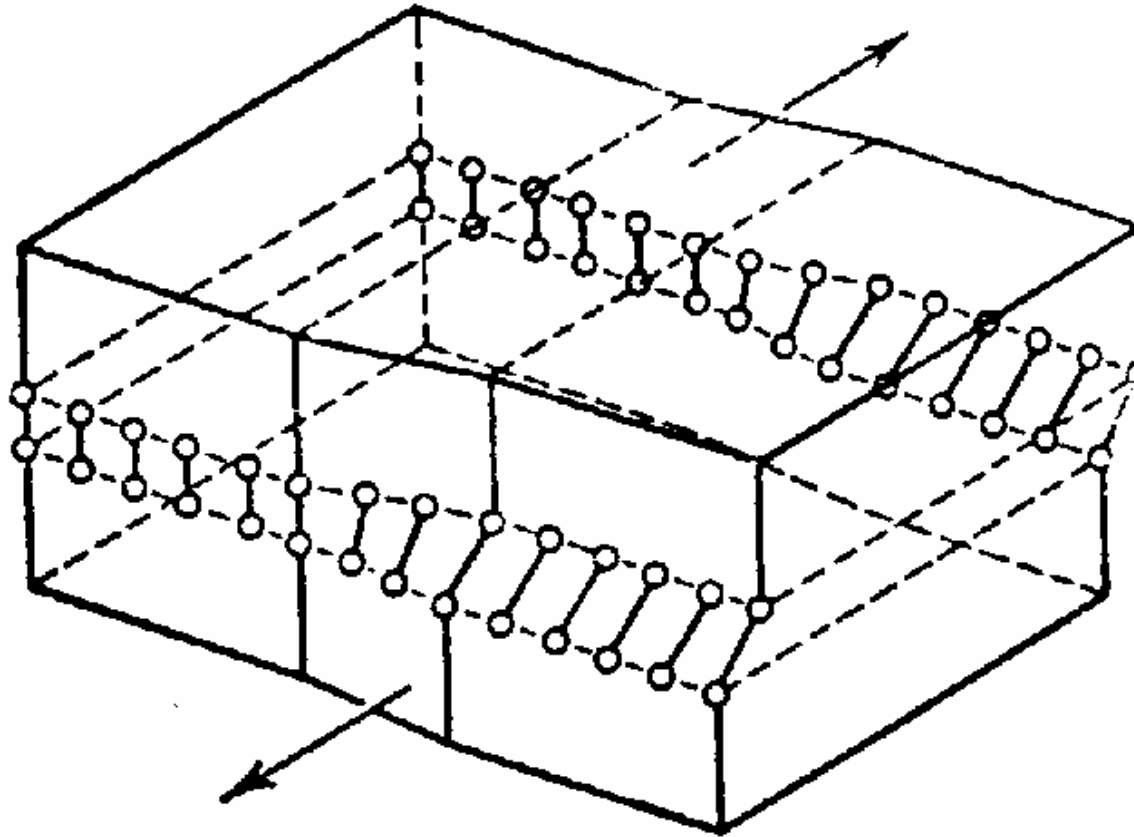


図 11-4 ラセン転位の構造*

制限資料

Strain rate by dislocation is proportional to density and velocity of dislocation.

$$\dot{\varepsilon} = C' \rho v$$

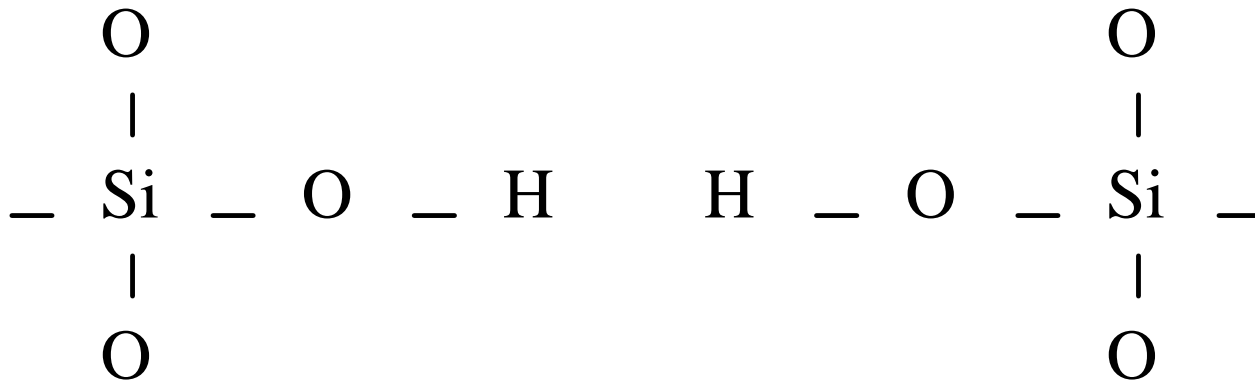
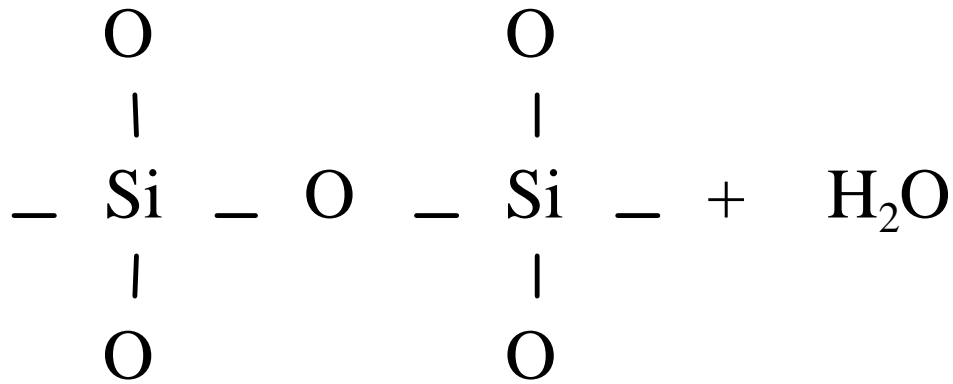
Density and velocity of dislocation is proportional to square of stress and stress, respectively.

$$\dot{\varepsilon} = C'' \sigma^3$$

- Strain rate by dislocation creep is proportional to cube of stress.
- Creep strain rate of minerals and rocks under high temperature sometimes proportional to the cube of stress.
- Existence of dislocation has not proven

Stress corrosion

- Corrosion of elongated and weakened atomic bonds by surround substances.
- Substances which cause corrosion
 - H_2O for SiO_2
 - CH_3CN for MgF_2



Crack velocity and stress intensity factor

■ Region 1

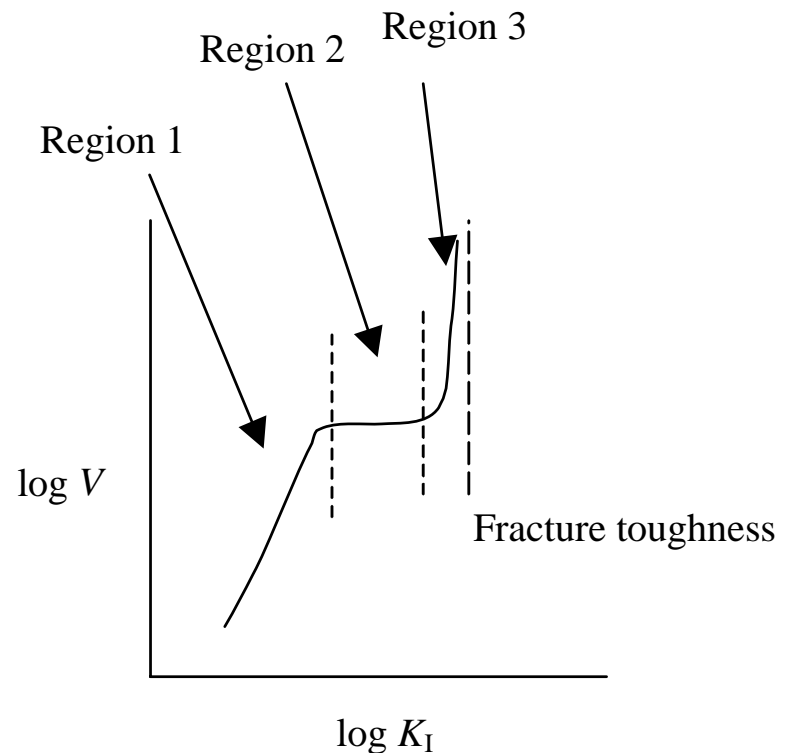
- Stress corrosion rate increases with stress intensity factor → crack velocity increases

■ Region 2

- Crack velocity is almost constant since diffusion velocity of the corrosion material determines the corrosion rate.
- This region would not be observed clearly for inhomogeneous materials.

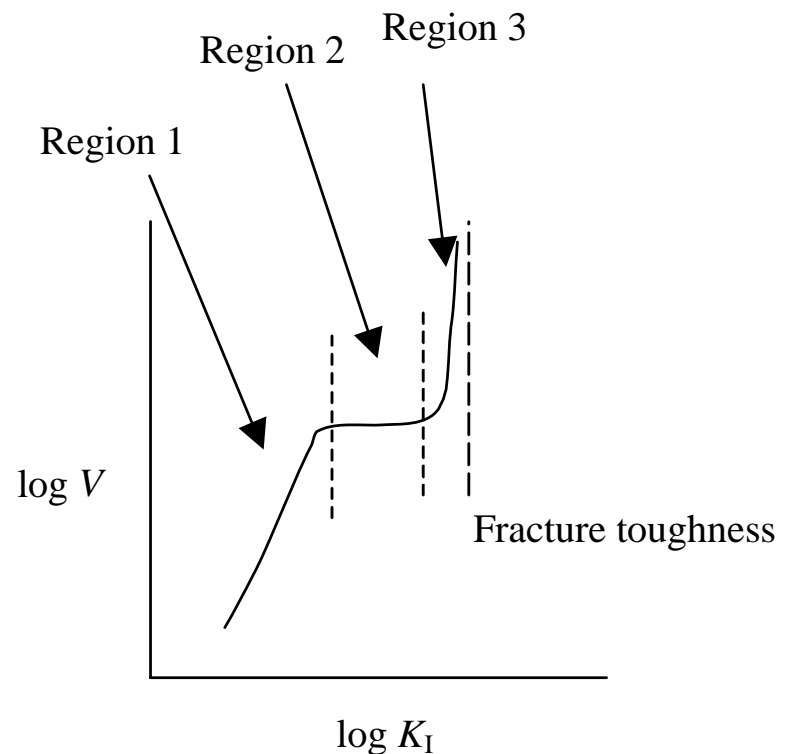
■ Region 3

- Failure due to mechanical elongation of atomic distance.

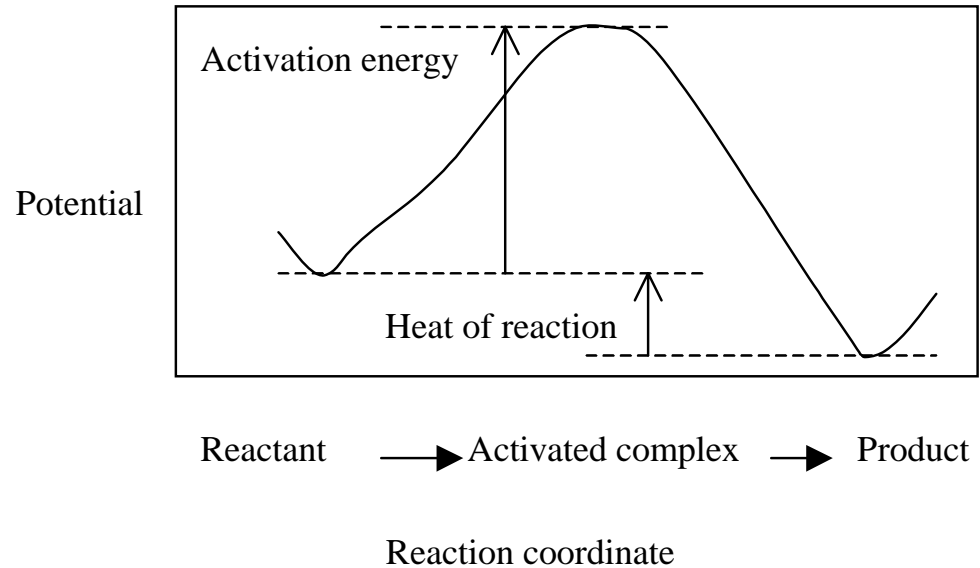


Upper limit of crack velocity

- 0.38 times P-wave velocity due to the limit of energy supply rate.
- The upper limit of velocity of fracture propagation in fault earthquake is velocity of Reyleigh wave (0.88~0.96 times S-wave velocity)
 - Difference in new fracture and propagation of slip along already fractured fault.



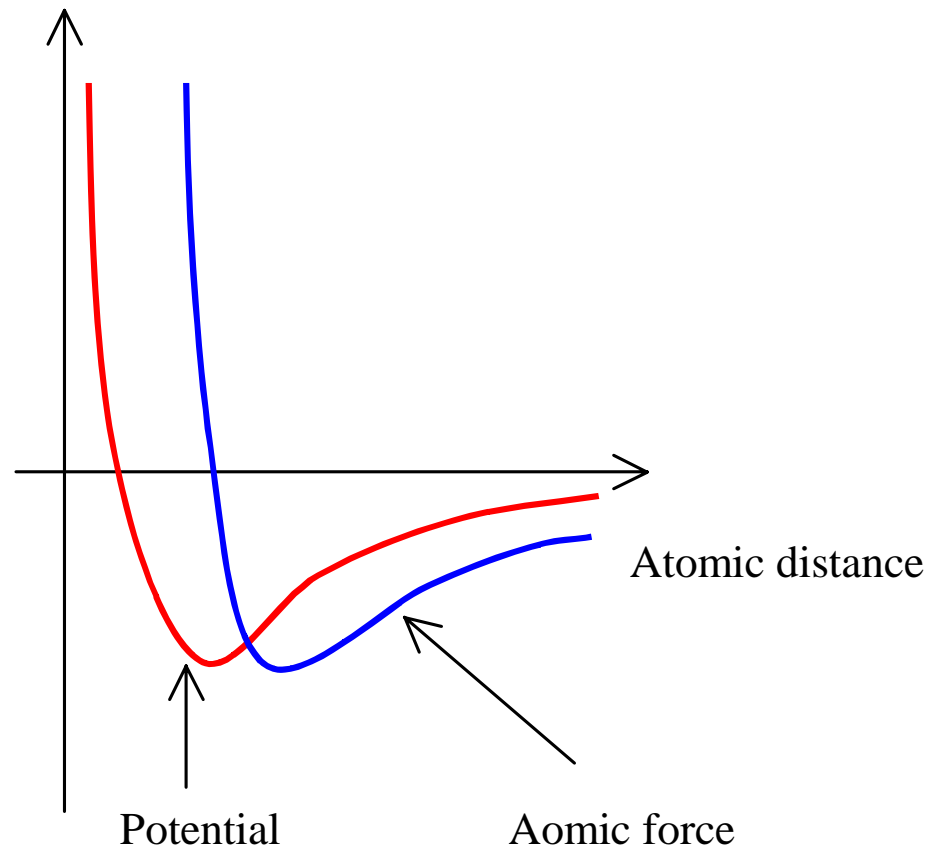
Activation energy



- Activation energy has to be exceeded for a reaction
 - The higher the energy, the higher the probability to exceed the activation energy
 - Increase in reaction rate - increase of crack velocity
- Number of reaction molecules and the density of corrosion material have a positive correlation in a certain density range

How to increase energy?

- Raising temperature (enthalpy)
- Elongation (potential)



$$V = V_0 a(\text{H}_2\text{O}) \exp\left(\frac{-E_{\text{act}} + \alpha K_{\text{I}}}{RT}\right)$$

$$\alpha = \frac{2V^*}{\sqrt{\pi r_c}}$$

Crack velocity in Region 1

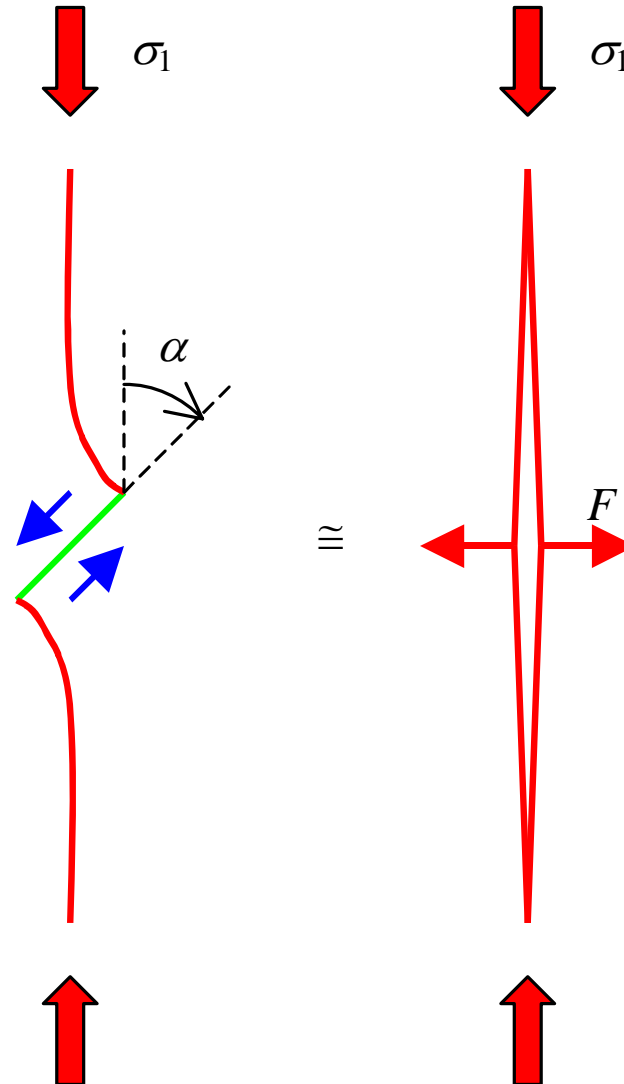
- V_0 (m/s) is a constant depending material and conditions
- $a(\text{H}_2\text{O})$ is the activity of water that is nearly equal to the relative humidity
- E_{act} (J/mol) is the activation energy per 1 mol
- K_{I} is the stress intensity factor for Mode I ($\text{Pa}\cdot\text{m}^{0.5}$)
- R is the gas constant ($8.3144 \text{ J K}^{-1} \text{ mol}^{-1}$)
- T is the absolute temperature (K)
- V^* is the volume of activation
- r_c is the radius of curvature at crack tip
- Value in the parenthesis is below zero.
- V_0 is the value of V when the value in the parenthesis is zero, namely, infinite high temperature or $\alpha K_{\text{I}} = E_{\text{act}}$
- Crack velocity decreases with decrease of temperature from infinite high temperature or decrease of stress intensity from E_{act}/α

- Q: Crack velocity of a rock under a small stress is 1 mm/s and 10 mm/s at 30°C and 200°C, respectively. Estimate crack velocity at 0°C.
- A: 0.497 mm/s

Explanation of primary creep based on stress corrosion

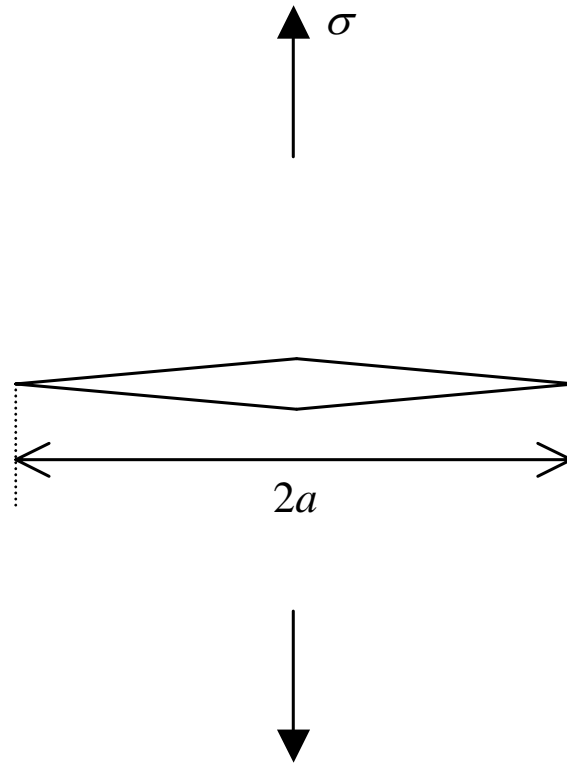
$$K_I = \frac{F}{\sqrt{\pi l}}$$

- The longer the crack grows,
 - The smaller the stress intensity factor becomes
 - Crack velocity decreases
 - Strain rate decreases



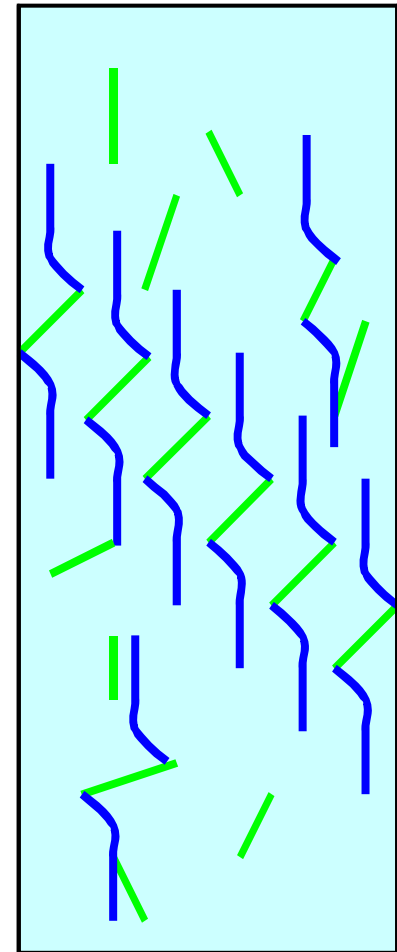
$$K_I = \sigma \sqrt{\pi a}$$

- When the crack grows under tensile stress, stress intensity increases.
 - Primary creep shouldn't appear but was observed.



Explanation of tertiary creep based on stress corrosion

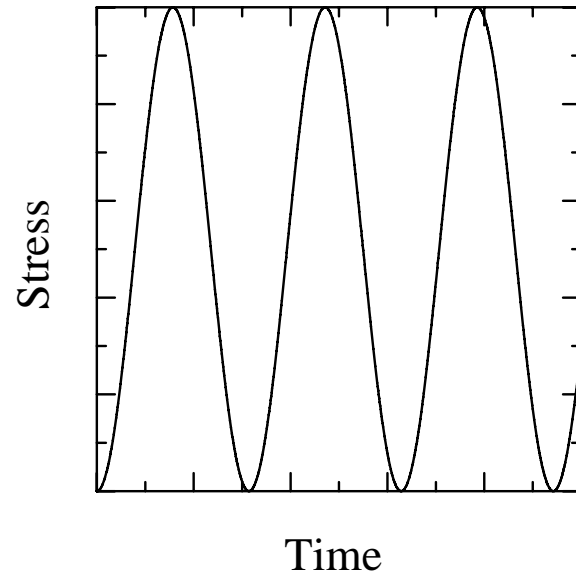
- When crack density exceeds a certain limit, stress intensity factor increases due to interferences between the cracks
 - Crack velocity increases.
 - Strain rate increases.



6.5 Fatigue failure

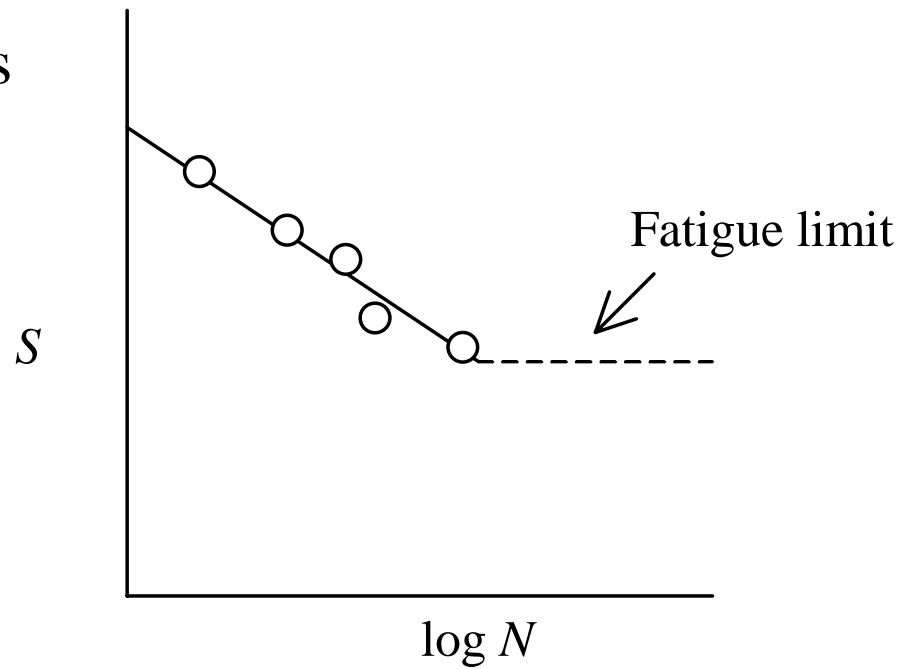
Fatigue failure?

- Failure due to cyclic loading
 - Fatigue failures of metallic parts is causes of many accidents of airplanes, nuclear power plants.



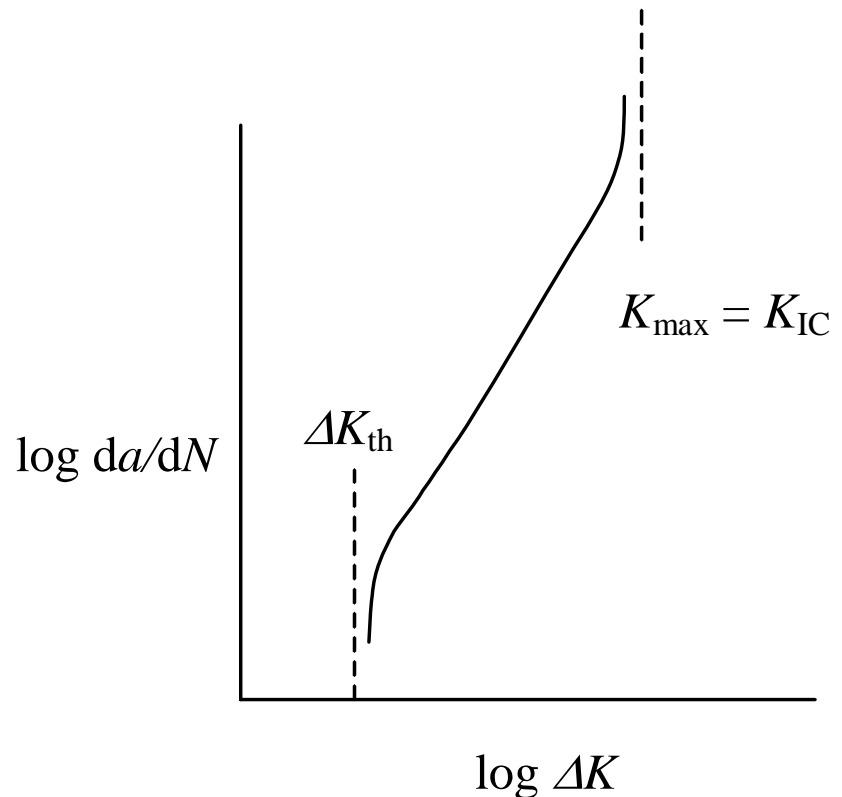
S - N curve

- S : stress amplitude
- N : number of cycles

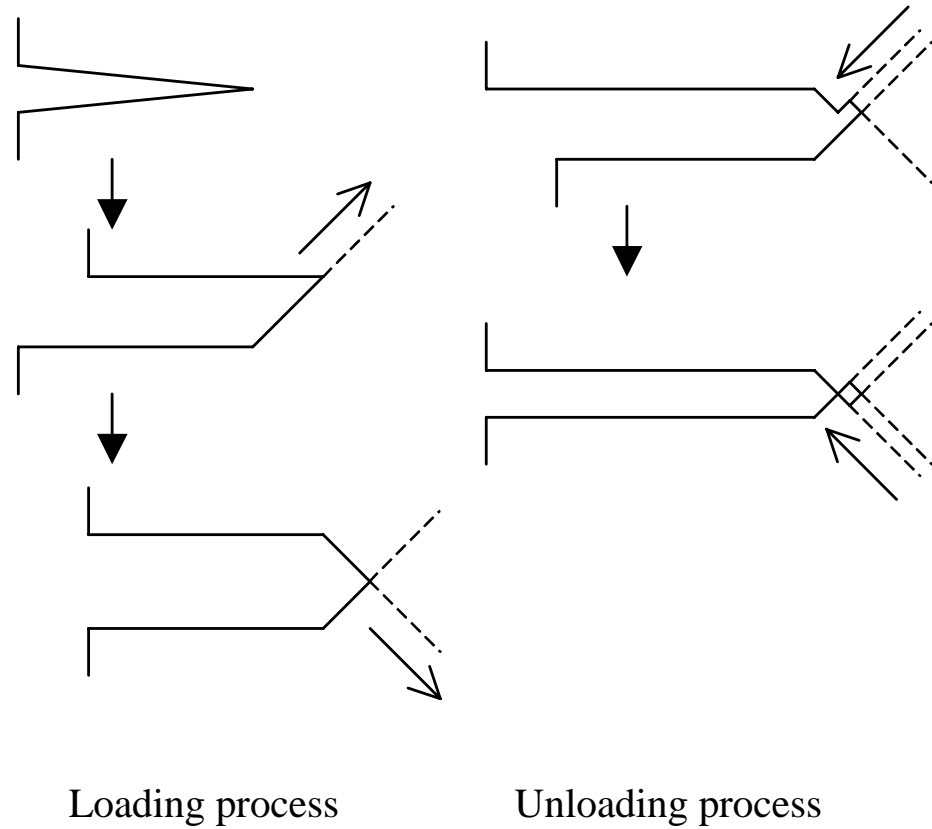


Characteristics of fatigue crack growth

- da/dN : increment of crack length in a loading cycle
- ΔK_{th} : lower limit of stress intensity factor amplitude
 - Crack never grow under stress intensity factor below the limit.



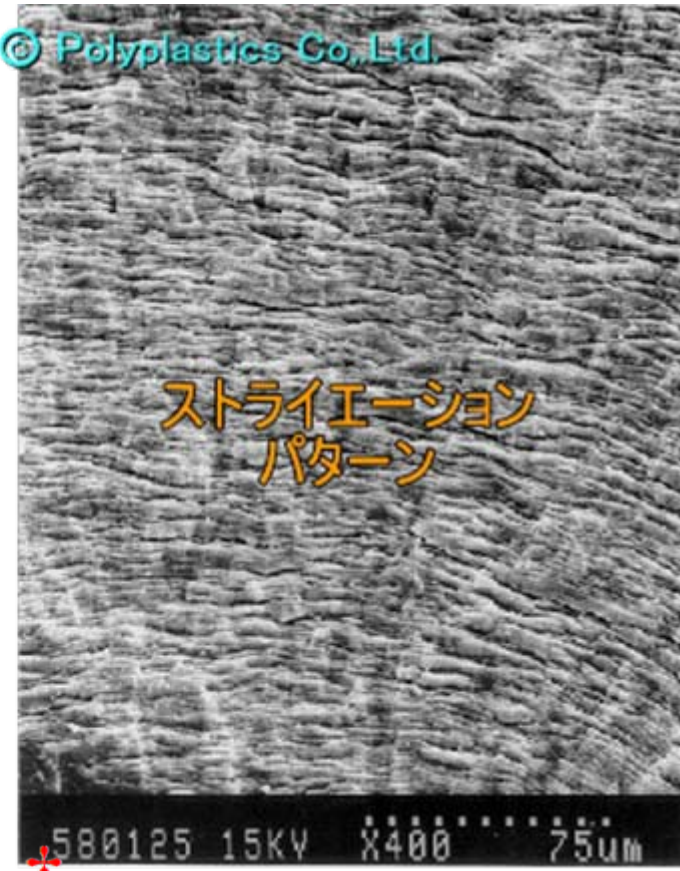
Mechanism of fatigue



Characteristics of fatigue crack



制限資料



制限資料

PLAMOS web-site内
「http://www.plamos.com/html/support/s_10_03_04.html」
に掲載してある電顕写真

Striation pattern

- Fatigue crack grows in plastic regions which were created by the crack itself.
- There are many oxidized or corroded materials at crack surfaces.
- They prevent crack growth under very small stress intensity amplitude

Fatigue crack of rock

- Time to failure becomes maximum at a certain stress amplitude.

